

COURSE NAME:  
**DATA WAREHOUSING & DATA MINING**

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# LECTURE 19

## TOPICS TO BE COVERED:

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- ✘ Other Classification Methods
  - + Genetic Algorithm
  - + Rough Sets
  - + Fuzzy techniques
  - + Support Vector Machines

# OTHER CLASSIFICATION METHODS

- ✘ Genetic algorithm
- ✘ Rough set approach
- ✘ Fuzzy set approaches

# GENETIC ALGORITHMS

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- ✘ In genetic algorithms, populations of rules “evolve” via operations of crossover and mutation until all rules within a population satisfy a specified threshold.
- ✘ GA: based on an analogy to biological evolution
- ✘ Each rule is represented by a string of bits
- ✘ An initial population is created consisting of randomly generated rules

# GENETIC ALGORITHMS

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- ✘ As a simple example, suppose that samples in a given training set are described by two Boolean attributes,  $A_1$  and  $A_2$ , and that there are two classes,  $C_1$  and  $C_2$ . The rule *“IF  $A_1$  AND NOT  $A_2$  THEN  $C_2$ ”* can be encoded as the bit string “100,” where the two leftmost bits represent attributes  $A_1$  and  $A_2$ , respectively, and the rightmost bit represents the class. Similarly, the rule *“IF NOT  $A_1$  AND NOT  $A_2$  THEN  $C_1$ ”* can be encoded as “001.” If an attribute has  $k$  values, where  $k > 2$ , then  $k$  bits may be used to encode the attribute’s values. Classes can be encoded in a similar fashion.

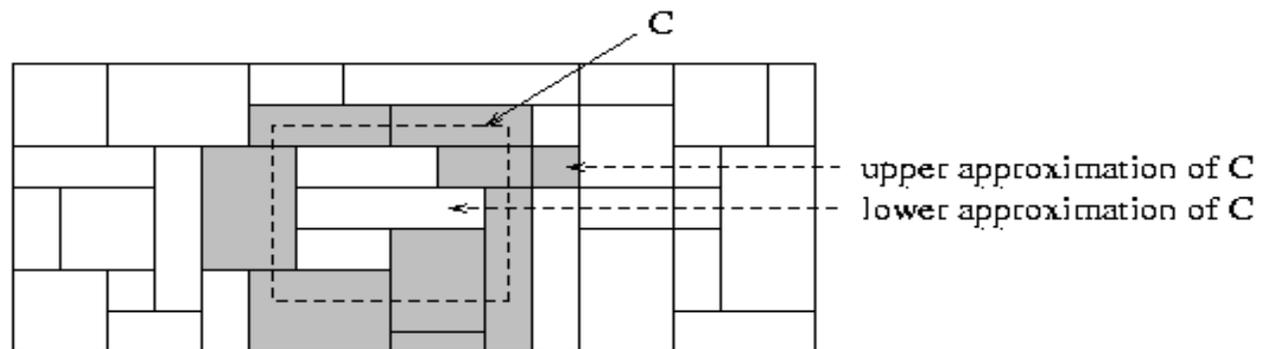
# GENETIC ALGORITHMS

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- ✘ Based on the notion of survival of the fittest, a new population is formed to consist of the *fittest rules in the current population, as well as offspring of these rules*. Typically, the fitness of a rule is assessed by its classification accuracy on a set of training samples.
- ✘ Offspring are created by applying genetic operators such as crossover and mutation.
- ✘ In crossover, substrings from pairs of rules are swapped to form new pairs of rules. In mutation, randomly selected bits in a rule's string are inverted.
- ✘ The process of generating new populations based on prior populations of rules continues until a population,  $P$ , evolves where each rule in  $P$  satisfies a prespecified fitness threshold.

# ROUGH SET APPROACH

- ✘ Rough sets are used to approximately or “roughly” define equivalent classes
- ✘ A rough set for a given class  $C$  is approximated by two sets: a **lower approximation** (certain to be in  $C$ ) and an **upper approximation** (cannot be described as not belonging to  $C$ )
- ✘ Finding the minimal subsets (reducts) of attributes (for feature reduction) is NP-hard but a discernibility matrix is used to reduce the computation intensity



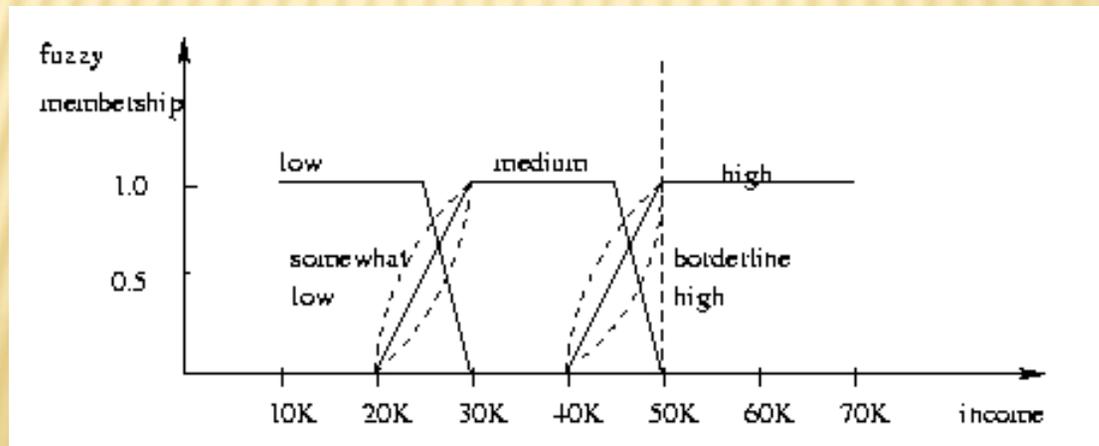
# ROUGH SET APPROACH

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- ✘ The lower and upper approximations for a class  $C$  are shown in Figure ,where each rectangular region represents an equivalence class. Decision rules can be generated for each class. Typically, a decision table is used to represent the rules.
- ✘ Rough set theory can be used to approximately define classes that are not distinguishable based on the available attributes

# FUZZY SETS

- ✘ Fuzzy logic uses truth values between 0.0 and 1.0 to represent the degree of membership (such as using **fuzzy membership graph**)
- ✘ Attribute values are converted to fuzzy values
  - + e.g., income is mapped into the discrete categories {low, medium, high} with fuzzy values calculated



# FUZZY SETS

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- ✘ For a given new sample, more than one fuzzy value may apply
- ✘ Each applicable rule contributes a vote for membership in the categories
- ✘ Typically, the truth values for each predicted category are summed
  
- ✘ Fuzzy set approaches replace “brittle” threshold cutoffs for continuous-valued attributes with degree of membership functions.

# HISTORY OF SVM (SUPPORT VECTOR MACHINES)

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- SVM is related to statistical learning theory
- SVM was first introduced in 1992
- SVM becomes popular because of its success in handwritten digit recognition
  - 1.1% test error rate for SVM. This is the same as the error rates of a carefully constructed neural network, LeNet 4.
- SVM is now regarded as an important example of “kernel methods”, one of the key area in machine learning
  - Note: the meaning of “kernel” is different from the “kernel” function for Parzen windows

# SUPPORT VECTOR MACHINE

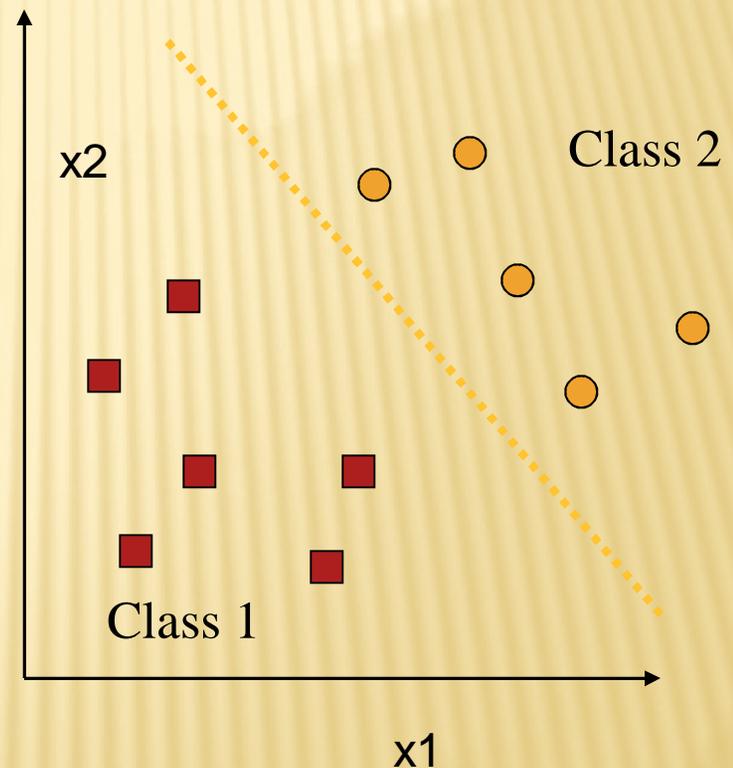
- ✦ A Support Vector Machine (SVM) is an algorithm for the classification of both linear and nonlinear data. It transforms the original data in a higher dimension, from where it can find a hyperplane for separation of the data using essential training tuples called support vectors.

# SUPPORT VECTOR MACHINE

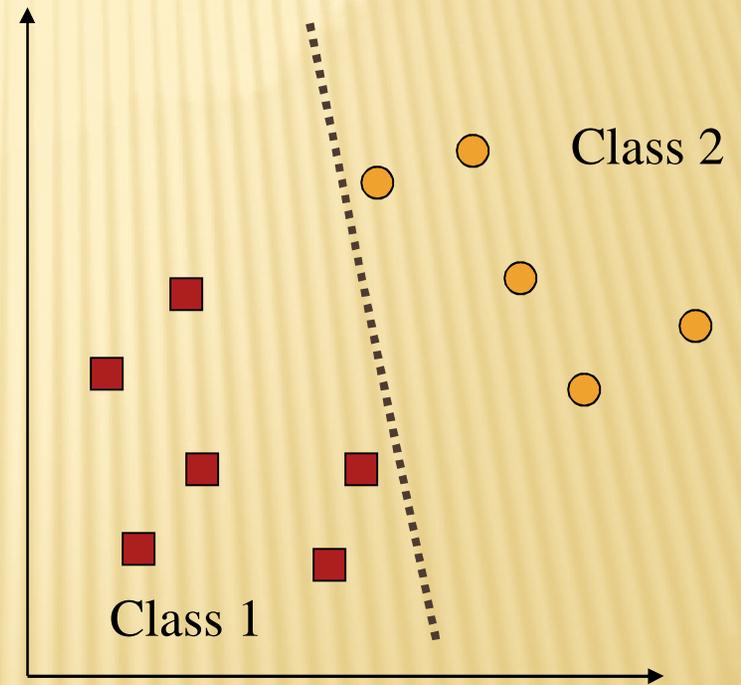
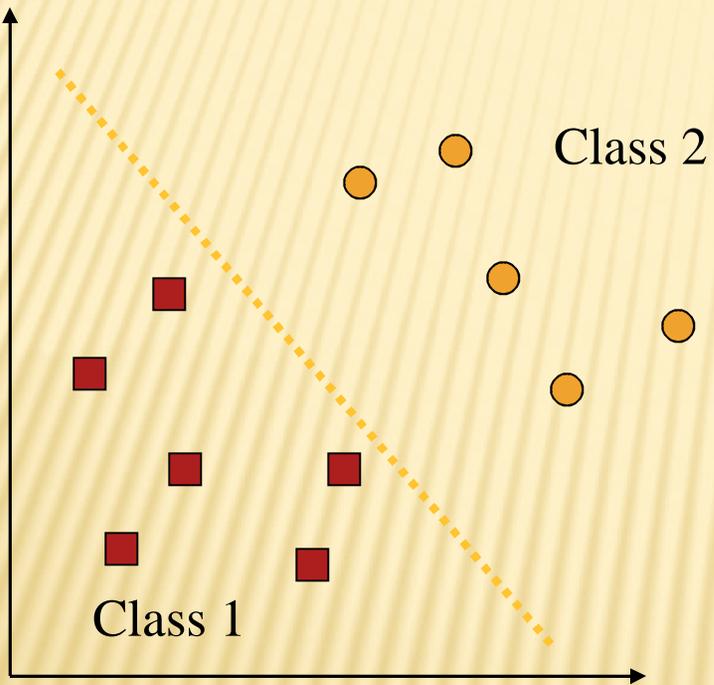
- ✘ The training time of even the fastest SVMs can be
- ✘ extremely slow, they are highly accurate, owing to their ability to model complex nonlinear decision boundaries.
- ✘ They are much less prone to overfitting than other methods.
- ✘ The support vectors found also provide a compact description of the learned model.
- ✘ SVMs can be used for prediction as well as classification.
- ✘ They have been applied to a number of areas, including handwritten digit recognition, object recognition, and speaker identification, as well as benchmark time-series prediction tests.

# WHAT IS A GOOD DECISION BOUNDARY?

- ✗ Consider a two-class, linearly separable classification problem
- ✗ Many decision boundaries!
  - + The Perceptron algorithm can be used to find such a boundary
  - + Different algorithms have been proposed
- ✗ Are all decision boundaries equally good?



# EXAMPLES OF BAD DECISION BOUNDARIES



# THE CASE WHEN THE DATA ARE LINEARLY SEPARABLE

- ✘ To explain the mystery of SVMs, let's first look at the simplest case—a two-class problem where the classes are linearly separable.
- ✘ Let the data set  $D$  be given as  $(X_1, y_1), (X_2, y_2), \dots, (X_{|D|}, y_{|D|})$ , where  $X_i$  is **the set of training tuples with associated class labels,  $y_i$** .
- ✘ Each  $y_i$  can take one of two values, either  $+1$  or  $-1$  (i.e.,  $y_i \in \{1, -1\}$ ), corresponding to the classes *buys\_computer = yes* and *buys\_computer = no*, respectively.
- ✘ *To aid in visualization*, let's consider an example based on two input attributes,  $A1$  and  $A2$ , as shown in Figure next slide. From the graph, we see that the 2-D data are linearly separable because a straight line can be drawn to separate all of the tuples of class  $+1$  from all of the tuples of class  $-1$ .

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- ✘ A separating hyperplane can be written as

$$W \cdot X + b = 0;$$

- ✘ Where ***W*** is a weight vector, namely,

$$W = \{w_1, w_2, \dots, w_n\};$$

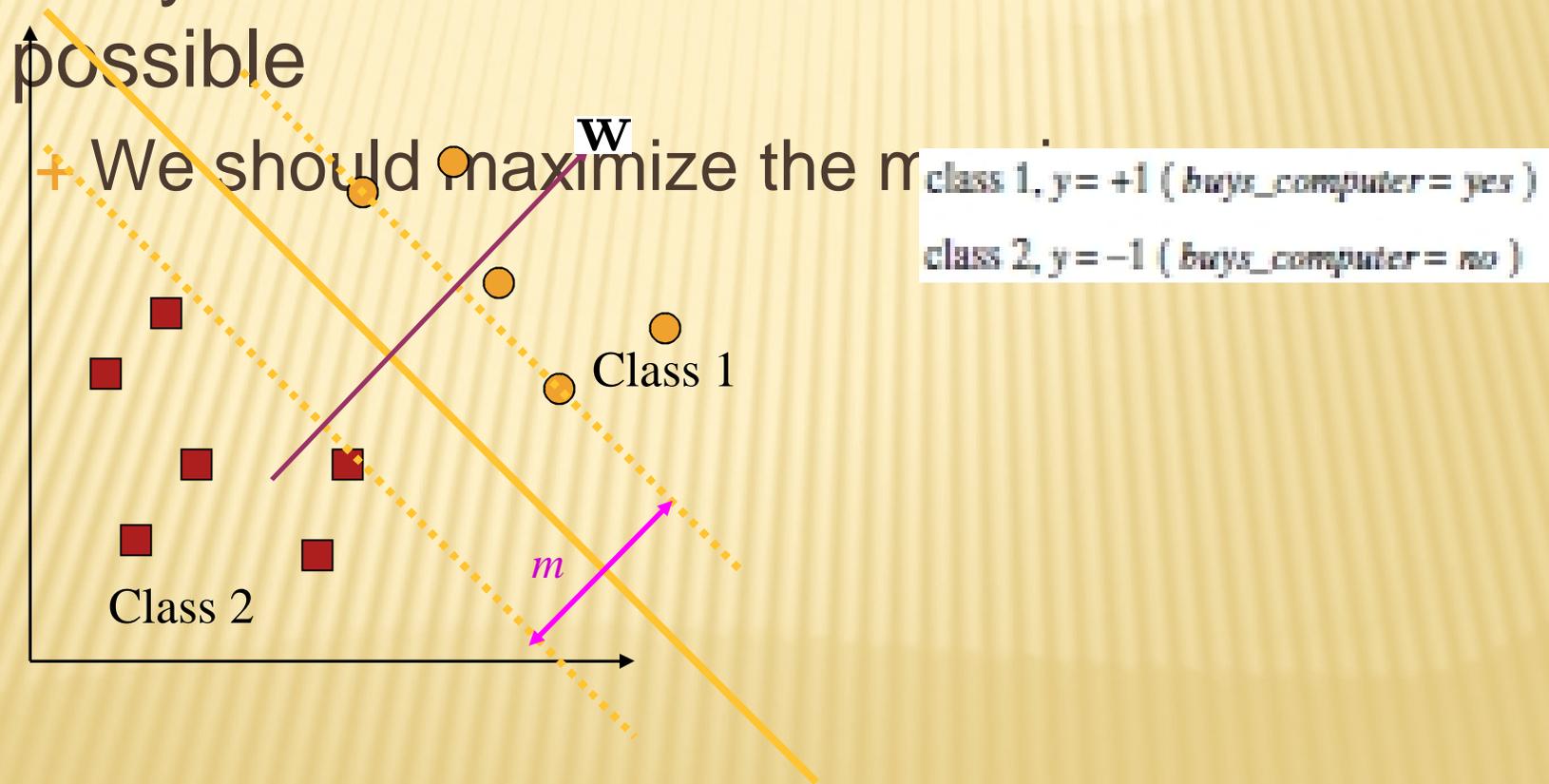
- ✘ ***n*** is the number of attributes;

- ✘ and ***b*** is a scalar, often referred to as a bias.

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# LARGE-MARGIN DECISION BOUNDARY

- ✗ The decision boundary should be as far away from the data of both classes as possible



- ✘ Training tuples are 2-D, e.g.,  $X = (x_1, x_2)$ ,
- ✘ where  $x_1$  and  $x_2$  are the values of attributes  $A_1$  and  $A_2$ , respectively, for  $X$ . If we think of  $b$  as an additional weight,  $w_0$ , we can rewrite the above separating hyperplane as

$$w_0 + w_1x_1 + w_2x_2 = 0$$

- ✘ Thus, any point that lies above the separating hyperplane satisfies

$$w_0 + w_1x_1 + w_2x_2 > 0$$

- ✘ Similarly, any point that lies below the separating hyperplane satisfies

$$w_0 + w_1x_1 + w_2x_2 < 0$$

## THE CASE WHEN THE DATA ARE LINEARLY INSEPARABLE

- ✘ The approach described for linear SVMs can be extended to create *nonlinear SVMs for the classification of linearly inseparable data (also called nonlinearly separable data, or nonlinear data, for short)*. Such SVMs are capable of finding nonlinear decision boundaries (i.e., nonlinear hypersurfaces) in input space.
- ✘ SVM by extending the approach for linear SVMs as follows. There are two main steps.
- ✘ In the first step, we transform the original input data into a higher dimensional space using a nonlinear mapping. Several common nonlinear mappings can be used in this step.
- ✘ The second step searches for a linear separating hyperplane in the new space. We again end up with a quadratic optimization problem that can be solved using the linear SVM formulation. The maximal marginal hyperplane found in the new space corresponds to a nonlinear separating hypersurface in the original space.

# STRENGTHS AND WEAKNESSES OF SVM

## × Strengths

- + Training is relatively easy
  - × No local optimal, unlike in neural networks
- + It scales relatively well to high dimensional data
- + Tradeoff between classifier complexity and error can be controlled explicitly
- + Non-traditional data like strings and trees can be used as input to SVM, instead of feature vectors
- + Inherent feature selection capability

## × Weaknesses

- + Need to choose a “good” kernel function.